

# MECÁNICA

## FUERZAS

$$\left\{ \begin{array}{l} \text{Gravitatoria} \quad \vec{F}_g = -G \frac{mM}{r^2} \vec{u} \\ \text{Electromagnética} \quad \vec{F} = K_e \frac{Qq}{r^2} \vec{u}_r = q \vec{E} \end{array} \right.$$

$$\vec{r} = \frac{m}{M} \vec{u}_r$$

## LEYES DE NEWTON

1ª → Si  $\vec{F}=0 \Rightarrow \vec{v}=cte$  Para partículas libres (sin Fuerzas)  $\Rightarrow \vec{a}=0$

$$2ª \rightarrow \sum \vec{F}_{ext} = \frac{d\vec{p}}{dt} = m \cdot \vec{a}$$

$$3ª \rightarrow \vec{F}_{12} = -\vec{F}_{21} \quad \vec{p}_{tot} = cte$$

## SISTEMAS DE REFERENCIA INERCIALES

$\vec{a}=0$  "de un S. Ref. sobre el otro"

- Cambio Origen coordenadas "Con mov. uniforme de S'/S"  $\vec{p}=cte$

- Giro  $\vec{L}=cte$

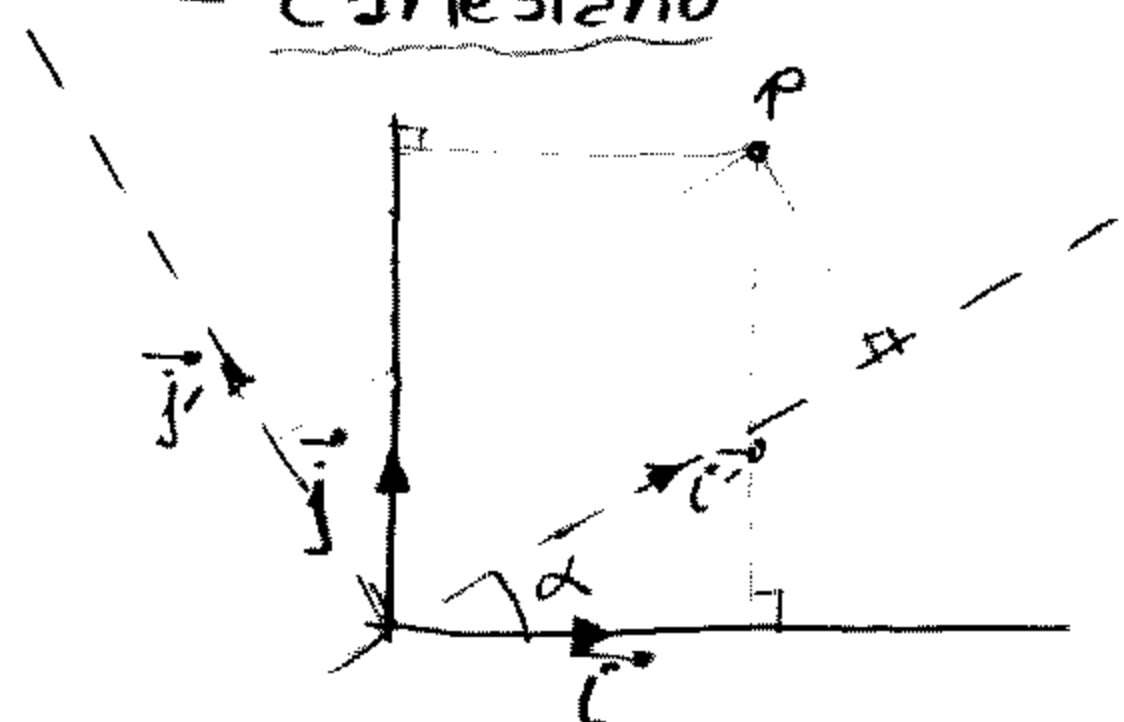
$$\vec{v}' \Rightarrow \vec{E}=cte$$

- Rotación

$$\vec{v} \cdot \vec{u} = cte \quad \vec{v}$$

## SISTEMAS DE COORDENADAS

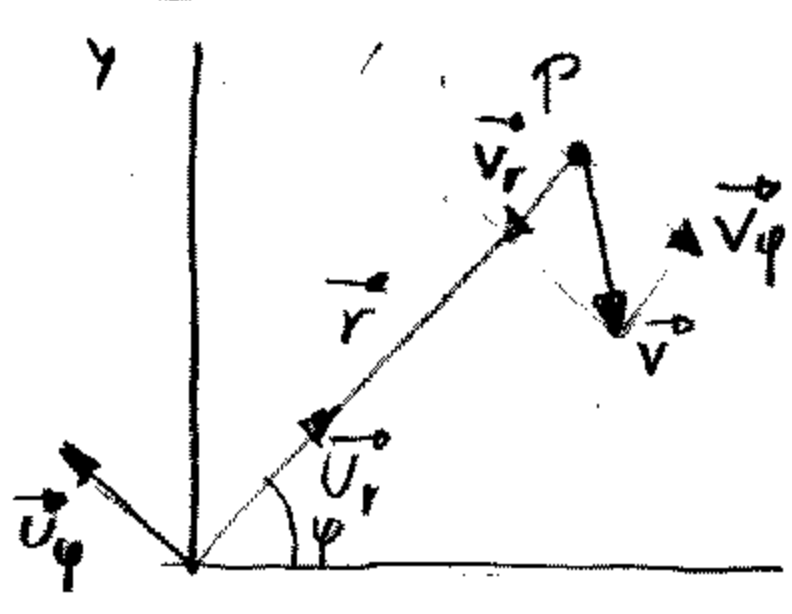
- Cartesiano



$$\begin{pmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{pmatrix} \begin{pmatrix} \vec{i} \\ \vec{j} \end{pmatrix} = \begin{pmatrix} \vec{i}' \\ \vec{j}' \end{pmatrix}$$

$$(x, y) \rightarrow \vec{r} = x\vec{i} + y\vec{j}$$

- Polares

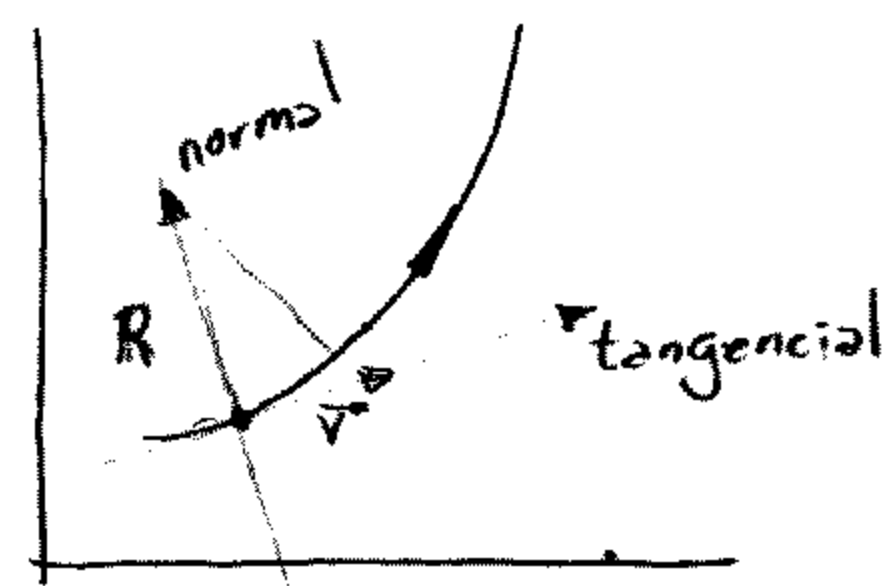


$$v_r = \frac{dr}{dt} \quad v_\varphi = r\omega$$

$$\vec{v} = v_r \vec{u}_r + v_\varphi \vec{u}_\varphi \quad \vec{u}_r = \frac{\vec{r}}{r}$$

$$(r, \varphi) \rightarrow \vec{r} = r \vec{u}_r$$

- Intrínsecas



$$\vec{a}_t = \frac{d\vec{v}}{dt} \quad a_n = \frac{v^2}{R} \quad u_t = \frac{\vec{v}}{|\vec{v}|}$$

$$\vec{v} = v \vec{u}_t \quad v = |\vec{v}| \rightarrow \text{celeridad}$$

## TRABAJO Y ENERGÍA CINÉTICA

$$W = \frac{1}{2} m \Delta v^2 = E_{k_f} - E_{k_0}$$

$$P = \vec{F} \cdot \vec{v} = \frac{dW}{dt}$$

$$W = \int \vec{F} \cdot d\vec{r}$$

## FUERZAS CONSERVATIVAS Y ENERGÍA POTENCIAL

$$\Delta U = - \int_a^b \vec{F} \cdot d\vec{r} = -W_{cons}$$

$$\vec{F} = -\nabla U = - \left( \frac{\partial U}{\partial x} \vec{i} + \frac{\partial U}{\partial y} \vec{j} + \frac{\partial U}{\partial z} \vec{k} \right)$$

$$\Delta U = -F \Delta r \cos \alpha$$

$$\vec{F} = - \left( \frac{\partial U}{\partial r} \vec{u}_r + \frac{\partial U}{\partial \theta} \vec{u}_\theta \right)$$

## MOMENTO CINÉTICO

F puramente radial  $\Rightarrow \vec{L}=cte$

- Momento de una Fuerza

$$\vec{M} = \vec{r} \wedge \vec{F} = rF \sin \theta \vec{k} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix}$$

$$\vec{L} = \vec{r} \wedge \vec{p}$$

$$\vec{M} = \frac{d\vec{L}}{dt}$$

- En un M.C.U

$$\vec{L} = -m\omega r^2 \Rightarrow cte \Rightarrow \vec{M} = 0$$

$$\begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ x & y & z \\ \dot{x} & \dot{y} & \dot{z} \end{vmatrix} = m(x\dot{y}z - y\dot{z}x)$$

# SISTEMAS PARTICULAS

$$\vec{r}_{cm} = \frac{\sum \vec{r}_i m_i}{M} ; \quad \vec{v}_{cm} = \frac{\vec{P}}{M} \Rightarrow \boxed{\vec{p} = M\vec{v}_{cm}} ; \quad \frac{d\vec{p}}{dt} = \vec{F}_{ext}$$

$$\Delta(E_k + U_{ext} + \text{Autoenergía}) = \Delta E = W_{no. cons.}$$

- Cambio s.ref

$$SR_{cm} \rightarrow \boxed{E_k = E'_k + \frac{1}{2} M v_{cm}^2}$$

# TERMODINÁMICA

$$\boxed{PV = nRT}$$

$$\boxed{P = \frac{F}{S}}$$

$$U = \frac{1}{2} n N_A \frac{1}{2} kT = \frac{1}{2} nRT$$

$$R = k N_A = 8.31 \text{ J/K mol}$$

$$kT (T=300K) \approx 26 \text{ meV}$$

$$n = \frac{N}{N_A} ; N_A = 6.023 \cdot 10^{23} \text{ molecules/mol}$$

$$k = 1.38 \cdot 10^{-23} \text{ J/K}$$

$\nu \rightarrow$  gr. libertad accesibles

$$1 \text{ eV} = 1.6 \cdot 10^{-19} \text{ J}$$

$$E = qV = e \cdot 1V$$

$n \rightarrow$  no moles

$N \rightarrow$  part. totales

- Gases monoatómicos  $\rightarrow 3$

Bajos Temp  $\rightarrow 3$

Temp. amb  $\rightarrow 5$

Alts Temp  $\rightarrow 7$

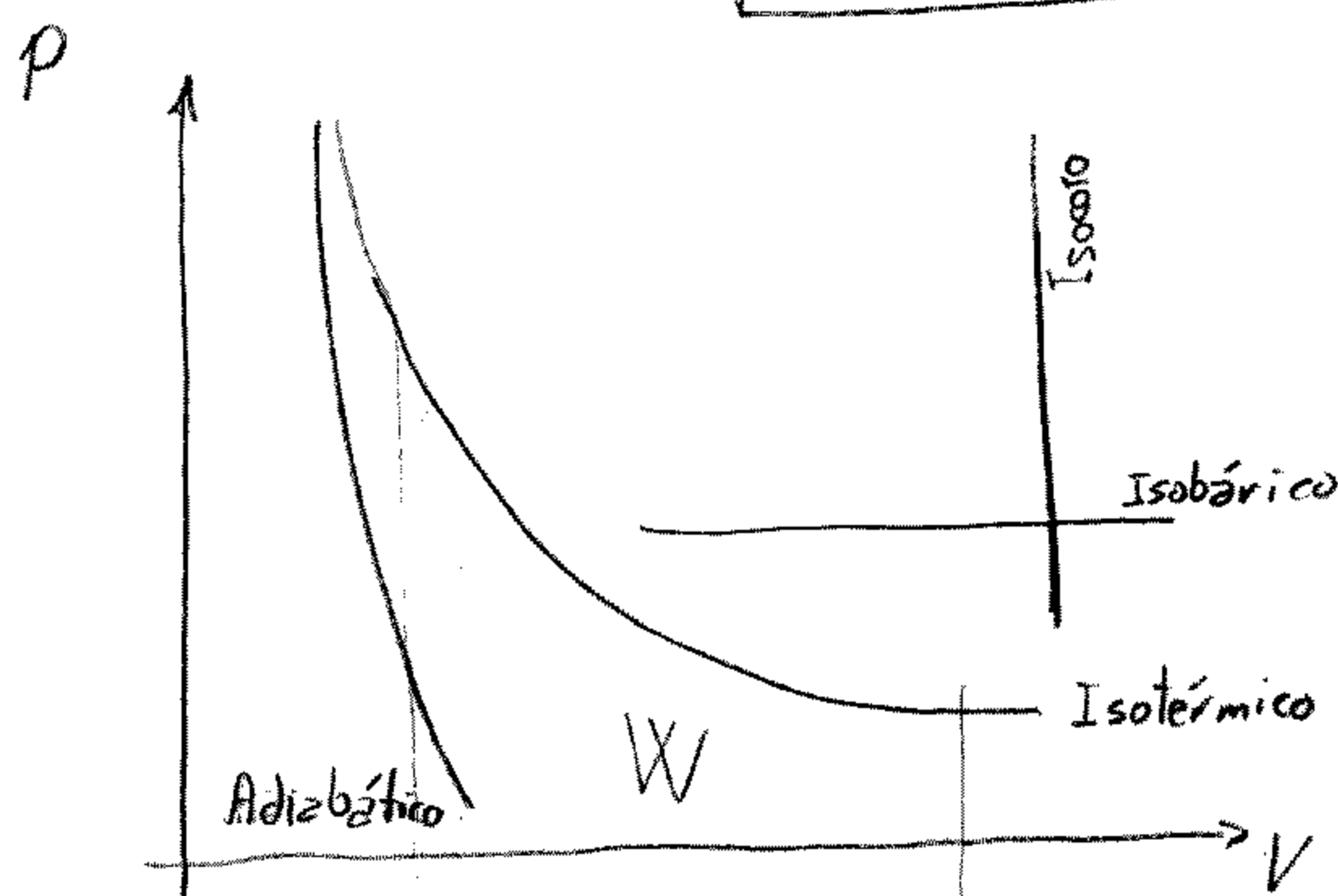
$$\boxed{Q = \Delta U + W}$$

$$W_{ab} = \int_a^b P dV = nRT_a \ln \left( \frac{V_b}{V_a} \right)$$

$$1 \text{ Pa} = 1 \text{ N/m}^2$$

$$1 \text{ atm} = 1.013 \cdot 10^5 \text{ Pa}$$

$$1 \text{ bar} = 10^5 \text{ Pa}$$



Isotérmico  $\rightarrow T = cte (U = cte) \rightarrow Q = W$

Isocoro  $\rightarrow V = cte (W = 0)$

Isobárico  $\rightarrow P = cte$   $W = P\Delta V$

Adiabático  $\rightarrow Q = cte^0$

$$\boxed{PV^\gamma = cte}$$

$$\gamma = \frac{\nu + 2}{\nu} = \frac{C_p}{C_v}$$

$$\boxed{C_v = \frac{Q}{\Delta T} \Big|_{V=cte} = \frac{\Delta U}{\Delta T} = \frac{\nu R}{2}}$$

$$\boxed{C_p = \frac{Q}{\Delta T} \Big|_{P=cte} = \frac{\Delta U + W}{\Delta T} = C_v + R = \frac{\nu R}{2} + R = R \left( 1 + \frac{\nu}{2} \right) = R \left( \frac{2 + \nu}{2} \right)}$$

# ONDAS

$$\boxed{y(x,t) = A \sin(\omega t + Kx)}$$

- Ondas transversales en la cuerda / Acústicas

$$\omega = 2\pi f ; k = \frac{2\pi}{\lambda} ; v = \lambda f$$

Acústica:  $E/\text{unid } V$   $V_p = \sqrt{\frac{T}{\mu}} = \frac{k}{\omega^2}$

$N = \frac{\text{masa}}{\text{longitud}} \rightarrow \rho$  sobrepresión (acústica)

$$\boxed{V_p = \omega \cdot y_0}$$

$$\boxed{Z_0 = \sqrt{T\mu} \rightarrow \sqrt{B\rho}}$$

$$\langle \eta \rangle = \left\langle \frac{\Delta E_x}{\Delta x} \right\rangle = \left\langle \frac{\Delta U}{\Delta x} \right\rangle = \frac{1}{4} \mu (\omega y_0)^2 = \frac{1}{4} F (k y_0)^2 = \frac{1}{2} \mu V_p^2 \rightarrow \frac{1}{2} \rho V_p^2$$

$$\boxed{\langle P \rangle = \frac{1}{2} \sqrt{T\mu} \dot{y}_0^2 = \frac{1}{2} Z_0 V_p^2}$$

sobrepresión  $\rightarrow \Delta p = -p \frac{\Delta V}{V} = B \frac{\Delta V}{V}$

$$\boxed{B = \gamma P}$$

$$\boxed{V_p = \sqrt{\frac{\gamma RT}{M \text{ mol}}}}$$

Analogías Cuerda/Acústicas

$$\mu = \rho$$

$$T = B$$

$$\boxed{E = \frac{1}{2} K A^2}$$

$$\boxed{P = \frac{E}{\Delta t}}$$

$$\boxed{I = \frac{P}{S}}$$

$$\boxed{I = I_0 e^{-BR}}$$

$$\boxed{y_r = 2A \cos\left(k \frac{r'-r}{2}\right) \sin\left(\omega t - k \frac{r'+r}{2}\right) = A_r \cos\left(\omega t - k \frac{r'+r}{2}\right)}$$

Interf: Constructive  $\leftrightarrow r'-r = n\lambda$

Destructive  $\leftrightarrow r'-r = (2n+1) \frac{\lambda}{2}$

# OSCILACIONES

$$m \frac{d^2x}{dt^2} + b \frac{dx}{dt} + kx = F_{ext} \Rightarrow \frac{d^2x}{dt^2} + \frac{1}{\zeta} \frac{dx}{dt} + \omega_0^2 x = \frac{F_{ext}}{m}$$

$\left\{ \begin{array}{l} - \text{MAS} \Rightarrow b=0; \zeta=\infty \\ - \text{Osc. Lib. Amor} \Rightarrow F_{ext}=0 \\ - \text{Osc. Forzado} \end{array} \right.$

## - Analogías Mecánico-Eléctrico

$x \rightarrow q$	$m \rightarrow L$
$v \rightarrow i(A)$	$b \rightarrow R$
$F \rightarrow V(V)$	$k \rightarrow 1/C$

$$\zeta = \frac{m}{b} = \frac{L}{R}$$

$$\omega_0^2 = \frac{k}{m} = \frac{1}{LC}$$

## - (MAS)

$$x(t) = A_0 \sin(\omega_0 t + \varphi_0) = A e^{i(\omega_0 t + \varphi_0)}$$

$$E = U + E_k = \frac{1}{2} m \omega_0^2 A^2 = \frac{1}{2} k x^2 + \frac{1}{2} m v^2$$

## - Oscilador Libre Amortiguado

$$x(t) = A e^{-\frac{t}{2\zeta}} \sin(\omega_d t + \varphi(0))$$

$$\omega_d = \omega_0 \sqrt{1 - \frac{1}{4Q^2}}$$

$$Q = \omega_0 \zeta \approx \omega_d \zeta$$

$$E(t) \approx \frac{1}{2} k A^2 e^{-t/\zeta} = E(0) e^{-t/\zeta}$$

## - Oscilador Forzado (Régimen permanente sinusoidal)

$$\left. \begin{array}{l} x_L(t) = A e^{-\frac{t}{2\zeta}} \sin(\omega_d t + \varphi(0)) \\ x_p(t) = \frac{v_0}{\omega} \sin(\omega t + \varphi(\omega)) \end{array} \right\} \begin{array}{l} x(t) = x_p(t) + x_L(t) \\ CI \rightarrow x(0) = x_p(0) + x_L(0) \\ \dot{x}(0) = v_p(0) + v_L(0) \end{array}$$

$$Z(\omega) = b + j \left( \omega m - \frac{k}{\omega} \right)$$

Resonancia  $\rightarrow$

$$\omega_0 = \sqrt{\frac{k}{m}}$$

$$Z_0 = \sqrt{\frac{L}{C}} = \sqrt{km} \quad \text{característica}$$

$$F(t) = F_0 e^{i\omega t} = m \frac{dv}{dt} + bv + k \int v dt \Rightarrow F_0 = m v_1 (j\omega) + b v_1 + \frac{k v_1}{j\omega} = v_1 Z(\omega)$$

$$v(t) = v_0 e^{i(\omega t + \varphi)} = v_1 e^{i\omega t}$$

$$v_0 = |v_1| = \frac{F_0}{|Z(\omega)|}; \quad \varphi = -\arg[Z(\omega)]$$

$$x_0 = \frac{v_0}{\omega}$$

$$\text{Ancho de Banda} \Rightarrow \Delta\omega = \frac{1}{\zeta}$$

$$E_{\text{BOBINA}} \quad \langle E_k(\omega) \rangle = \frac{1}{4} m v_0^2(\omega)$$

$$E_{\text{CONDENS}} \quad \langle U(\omega) \rangle = \frac{1}{4} k x_0^2(\omega)$$

$$\left\{ \begin{array}{l} \langle E_k(\omega) \rangle \\ \langle U(\omega) \rangle \end{array} \right. = \left( \frac{\omega}{\omega_0} \right)^2$$

$$\langle P \rangle = \frac{1}{2} b v_0^2 = \frac{1}{2} k \zeta^2$$

## - Otras fórmulas útiles

$$Z(\omega) = Z(\omega_0) + j Z_0 \left( \frac{\omega}{\omega_0} - \frac{\omega_0}{\omega} \right)$$